

Numerical Libraries for Scientific Computing

April 1, 2015

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Topics

- Numerical libraries for scientific computing
- Numerical libraries at SHARCNET
- Examples
 - Linear algebra
 - FFTW
 - ODE solvers
 - Optimization
 - GSL
 - Multiprecision with MPFUN
 - PETSc (PDE solvers)
- Q&A

General Interest Seminars 2015



Overview

Numerical Computing

- Linear algebra
- Nonlinear equations
- Optimization
- Interpolation/Approximation
- Integration and differentiation
- Solving ODEs
- Solving PDEs
- FFT
- Random numbers and stochastic simulations
- Special functions

More fundamental problems:

- Linear algebra
- Nonlinear equations
- Numerical integration
- ODE
- FFT
- Random numbers
- Special functions

Top Ten Algorithms for Science (Jack Dongarra 2000)

1. Metropolis Algorithm for Monte Carlo
2. Simplex Method for Linear Programming
3. **Krylov Subspace** Iteration Methods
4. The Decompositional Approach to Matrix Computations
5. The Fortran Optimizing Compiler
6. **QR** Algorithm for Computing Eigenvalues
7. Quicksort Algorithm for Sorting
8. **Fast Fourier Transform**
9. Integer Relation Detection
10. Fast Multipole Method

Linear Algebra

Common Linear Algebra Operations

- Basic linear algebra operations
- Solving linear systems $Ax = b$ via **LU** decomposition.
- Solving linear spd systems $Ax = b$, A spd, via Cholesky factorization.
- Solving least squares problem $\min \|b - Ax\|_2$ via **QR** algorithms.
- Solving eigenvalue problems $Ax = \lambda x$ via QR factorization.
- Solving generalized eigenvalue problems $Ax = \lambda Bx$.
- Calculating **singular value decomposition** $A = U\Sigma V^T$ via QR factorization.
- Solving linear systems via *iterative* methods.
- **Krylov** subspace methods (**KSM**), e.g. CG (converge guaranteed), BCG, QMR, GMRES, BiCGstab, CGS, etc. alone, might be slow.
- Commonly used along with **preconditioning**: $M^{-1}Ax = M^{-1}b$ as finding an approximate inverse of the original matrix. KSM with preconditioning is referred to **KSP** in PETSc.

Most commonly used **linear algebra libraries**

- **LINPACK** (1970s), succeeded by LAPACK.
- **EISPACK** (1970s), succeeded by LAPACK.
- **LAPACK** – Free Fortran subroutines, some C/C++ APIs available, variants:
 - ATLAS – automatically tuned linear algebra systems.
 - **ACML** (AMD).
 - CXML (**Compaq** diseased), ESSL (**IBM**), SCSL (**SGI**), etc.
 - **IMSL** (40+ old, now owned by **Rogue Waves**).
 - MLIB (**HP**).
 - **MKL** (Intel).
 - **NAG** (**Numerical Algorithms Group**), etc.
- **SuperLU** – Sparse direct solvers.
- **ScaLAPACK** – LAPACK for distributed systems.
- **SPAI** – Sparse approximate inverse.
- **PETSc** + **SLEPc** – iterative solvers, eigen solvers.
- See @netlib <http://www.netlib.org/> for more.

LAPACK

- BLAS level 1, 2 and 3 routines for basic linear algebra operations. The most famous one and studied extensively for high performance computing is matrix-matrix multiplication **DGEMM**. A famous name associated with DGEMM is **Goto Kazushige 後藤 和茂**, a Japanese researcher who devoted his life to making the world's fastest matrix-matrix multiplication code, used to benchmark world's fastest computers. Goto used ship stand alone DGEMM routines, often known as Goto library, best tuned for the target hardware, usually beats any other implementations!
- Drivers for solving various problems.
- In addition to math operands, most routines has auxiliary tuning parameters that one can fine tune to achieve the optimal performance on the target hardware.
- Freely available in Linux distributions.
- Originally written in Fortran 77, callable from Fortran 90, C/C++. C/C++ interfaces are available.
- For dense matrices only, not for sparse matrices.
- Does not include iterative solvers.

Linear algebra libraries (cont'd)

- **ARPACK** – A collection of Fortran 77 subroutines for solving large scale eigenvalue problems using **AR**noldi methods.
 - Allow to compute a few eigenvalues with users specified features.
 - Underlying solver used by MATLAB, Octave, Scilib and R, etc.
 - It can use any matrix storage format, with matrix operations done through “**reverse communication interface**” (RCI) to the calling procedure.
 - **ARPACK++** - C++ interface to ARPACK; **PARPACK** – Parallel ARPACK.
 - Minor modifications needed to install.

Alternatives:

- **BLOPEX**
- **PRIMME** – See a survey on eigenvalue solvers (Andreas Stathopoulos, 2006)
- **PETSc+SLEPc**
- **FEAST** – Fast, high performance eigensolver, already integrated into intel MKL 11.x
 - Includes both ready to use interfaces and RCI interfaces
 - Can compute all eigenvalues and eigenvectors for given search interval

Linear algebra libraries (cont'd)

- **PARDISO** – Package for solving dense and sparse linear systems.
- **Aztec** – For solving large linear sparse systems.
- **MUMPS** – A massive parallel direct sparse solver.
- **Hypre** - A library for solving large, sparse linear systems, using common **Krylov** subspace based methods. Contains a suite of **preconditioners**.

See also collections, e.g.:

- Intel MKL
- GSL
- Boost.Numerics
- Apache Commons Math (mostly java?)

Example: Solving linear system $Ax = b$ using LU decomposition. Let

$$A = LU$$

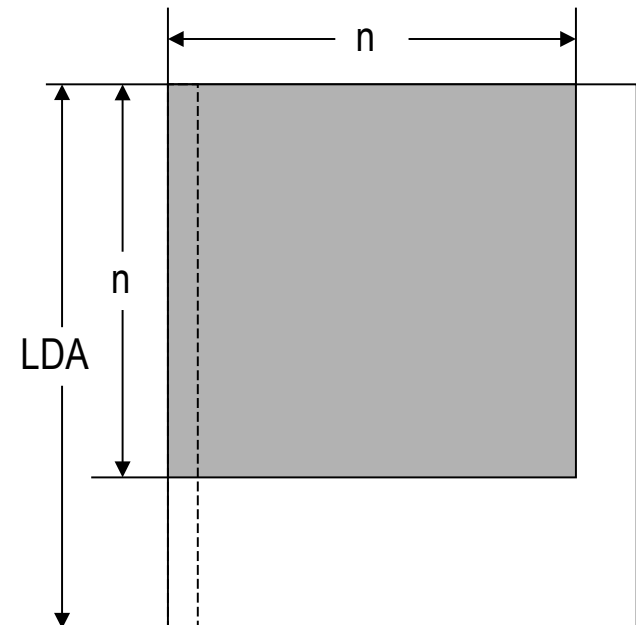
then $LUx = b$, we solve

$$Ly = b,$$

$$Ux = y.$$

This can be all done by one LAPACK subroutine **xGESV**

call dgesv(n, num_rhs, A, LDA, ipiv, x, LDA, info)



Example: (Cont'd) A by-product, we can compute the determinant of a matrix. For an n -by- n matrix, the determinant is defined as

$$\det(A) = \sum_{j_1, j_2, \dots, j_n} (-1)^{\sigma(j_1, j_2, \dots, j_n)} a_{ij_1} a_{ij_2} \cdots a_{ij_n}$$

where $\sigma(j_1, j_2, \dots, j_n)$ denotes the permutation of column indices.

Alternatively, via LU decomposition $A = PLU$

$$\begin{aligned} \det(A) &= \det(P) \det(L) \det(U) \\ &= (-1)^\sigma \det(U) \end{aligned}$$

This can be done with LAPACK subroutine **xGETRF** (with $x = d$ for double precision)

call dgetrf(n, n, A, LDA, ipiv, info)

The permutation of rows is stored in ipiv: ipiv[i] contains the index of row that is swapped with row i.

Example: Compute the eigenvalues $Ax = \lambda x$. Wilkinson test matrix: An n -by- n tridiagonal matrix, with diagonal elements

$$\frac{n-1}{2}, \frac{n-3}{2}, \frac{n-5}{n}, \dots, \frac{n-5}{n}, \frac{n-3}{2}, \frac{n-1}{2}$$

and 1's on off diagonals. The Wilkinson matrix of order seven looks as follows

$$A = \begin{bmatrix} 3 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 2 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 3 \end{bmatrix}.$$

The Wilkinson test matrix has a property that it has seeming the same eigenvalues in pairs, but they are really not the same. This may lead to the demand for higher precisions.

Example: Wilkinson matrix (cont'd). The LAPACK routine to use is

call **dsteval**('n', N, D, T, Z, DMAX, work, info)

On entry

- D – Vector containing the diagonal elements.
- T – Vector containing the off diagonal elements.

On return

- D – Contains eigenvalues.
- Z – Contains eigenvectors.

Example: Compute selected eigenvalues and eigenvectors of generalized **symmetric positive definite** eigenproblems

$$(1) \quad Ax = \lambda Bx$$

This can be done by the LAPACK subroutine **xSPGVX**, e.g.

```
call dspgvx( 1, 'N', 'I', 'U', n, A, B, VL, VU, iL, iU, 1, atol, &  
            num_eigs, eigs, eigv, 1, work, iwork, ifail, info )
```

But alternatively, we can separate the solution to (1) into two steps. Let $B = LU$, then we can write

$$Ax = \lambda LU$$

or

$$\Rightarrow L^{-1}Ax = \lambda Ux \quad \Rightarrow L^{-1}AU^{-1}Ux = \lambda Ux$$

$$L^{-1}AU^{-1}y = \lambda y,$$

$$Ux = y.$$

Remarks:

- The original generalized eigenvalue problem is separated into two problems: Part 1: LU (or Cholesky for *spd* matrices) factorization and Part 2: Solving a regular eigenvalue problem.
- Profiling the implementation of Part 1 and Part 2 shows 55+% vs. 45-% on execution time
- *“...It does the transformation from the Generalized Eigenvalue Problem to the Standard Eigenvalue Problem, using a new DAG algorithm and OpenMP. The Speed up for a 7000 by 7000 matrix is 1000 ! Yes 1000 times faster compared to the EISPACK routines which cannot be parallelized because of the data dependencies in the Cholesky algorithm.”* – Nick Chepurniy (former SHARCNET staff).

Multiprecision Packages

Example: Compute the eigenvalues of Wilkinson test matrix with higher than IEEE double precision.

The Wilkinson test matrix has a property that it has seemingly the same eigenvalues in pairs.

Really? This is where we need higher or arbitrary precisions.

For arbitrary precisions, two packages to consider:

- **GMP** (C/C++ interface)
- **MPFUN** (Fortran) or **ARPREC** (C++ implementation with C/C++ and Fortran interfaces)

```
-0.96413217269049067
0.21266284251310127
1.0781644067346108
1.6547300922541341
2.4007717515805513
2.6137235587096592
3.4862749555221253
3.5176393110600825
4.4989686209327697
4.5011924696537475
5.4999538446482141
5.5000502386255690
6.4999986232779925
6.5000014559541404
7.4999999704788101
7.5000000307300576
8.4999999995215454
8.5000000004932090
9.4999999999939302
9.5000000000062279
10.499999999999938
10.500000000000062
11.500000000000004
11.500000000000012
12.499999999999995
12.500000000000009
13.499999999999998
13.500000000000004
14.499999999999998
14.500000000000007
15.5000000000000616
15.5000000000000622
16.500000000054481
16.500000000054488
17.500000003808111
17.500000003808125
18.500000205070439
18.500000205070439
19.500008158672937
19.500008158672948
20.500225680185167
20.500225680185167
21.503952002665365
21.503952002665386
22.538941119306436
22.538941119306440
23.710678647333044
23.710678647333058
25.246194182903331
25.246194182903359
```

Fortran code using MPFUN

```

program steig
  use mpmodule
  implicit none
  type ( mp_real ), allocatable :: d(:), t(:), work(:), z(:, :)
  integer :: info, integer :: i, n, m, num_digits

  print *, 'Enter matrix size:'
  read *, n
  print *, 'Enter accuracy (number of digits):'
  read *, num_digits
  call mpinit( num_digits )
  call mpsetoutputprec( num_digits )

  allocate(d(n), t(n), z(n,n), work(2*n-2))

  create Wilkinson eigenvalue test matrix

  call imtql1(n, d, t, info)
  print *, 'Eigenvalues (Using EISPACK):'
  do i = 1, n
    call mpwrite( 6, c(i) )
  end do
end program steig

```

EISPACK subroutine

! This QL algorithm was written in the 1969s...

! We don't want to rewrite it!

```
subroutine imtql1(n,d,e,ierr)
```

```
  use mpmodule
```

```
  integer i,j,l,m,n,ii,mml,ierr
```

```
  type ( mp_real ) d(n),e(n)
```

```
  type ( mp_real ) b,c,f,g,p,r,s,tst1,tst2
```

c

c this subroutine is a translation of the algol procedure

c imtql1, num. math. 12, 377-383(1968) by martin and

c wilkinson,

c

... .. Rest of the code

... ..

return

end

With little effort – **three lines only** in this case – I was able to compute eigenvalues to arbitrary digits!

This example also shows the simplicity of Fortran superior to other languages for scientific computing.

Example: Computing eigenvalues of Wilkinson matrix of order n using double (15) and 40 digits

```

-0.96413217269049067
0.21266284251310127
1.0781644067346108
1.6547300922541341
2.4007717515805513
2.6137235587096592
3.4862749555221253
3.5176393110600825
4.4989686209327697
4.5011924696537475
5.4999538446482141
5.5000502386255690
6.4999986232779925
6.5000014559541404
7.499999704786101
7.5000000307300576
8.499999995215454
8.5000000004932090
9.499999999939302
9.50000000000062279
10.49999999999938
10.5000000000000062
11.5000000000000004
11.500000000000012
12.499999999999995
12.500000000000009
13.499999999999998
13.500000000000004
14.499999999999998
14.500000000000007
15.500000000000016
15.500000000000022
16.500000000054481
16.500000000054488
17.500000003808111
17.500000003808125
18.500000205070439
18.500000205070439
19.500008158672937
19.500008158672948
20.500225680185167
20.500225680185167
21.503952002665365
21.503952002665386
22.538941119306436
22.538941119306440
23.710678647333044
23.710678647333058
25.246194182903331
25.246194182903359

```

```

10 ^ -1 x -9.641321726904788469203807653558725272820102494785,
10 ^ -1 x 2.126628425131107295702128494459102204898454357475,
10 ^ 0 x 1.078164406734610586751527260933515250175346242597,
10 ^ 0 x 1.654730092254134485579766753257886141779285333348,
10 ^ 0 x 2.400771751580549653471719453673745125831512658936,
10 ^ 0 x 2.613723558709657970251705419366973354981509584181,
10 ^ 0 x 3.486274955522127377316131346219042782906283078552,
10 ^ 0 x 3.517639311060085206913357746819011821997391706608,
10 ^ 0 x 4.498968620932769352208565164016883576924323795219,
10 ^ 0 x 4.501192469653747967060030800142379067747029642296,
10 ^ 0 x 5.499953844648219428838229822039180544884672380507,
10 ^ 0 x 5.5000502386255744936146229202431453164635212134466,
10 ^ 0 x 6.499998623277988915591995913147693974561916204077,
10 ^ 0 x 6.500001455954136799897192333983951377820778801077,
10 ^ 0 x 7.49999970478611371657446880312535145009630930559,
10 ^ 0 x 7.50000003073005526457051748353478345759432546457,
10 ^ 0 x 8.49999999521540927978771807129468065254241367295,
10 ^ 0 x 8.500000000493206277760349451609484527161829931395,
10 ^ 0 x 9.49999999993923902705172850882166649743950242226,
10 ^ 0 x 9.5000000000006222657447847663151767192196337560297,
10 ^ 1 x 1.04999999999993785719572185114285224895492394635,
10 ^ 1 x 1.050000000000006335023029689638865159736459003164,
10 ^ 1 x 1.14999999999999947691728926053358946623871069579,
10 ^ 1 x 1.150000000000000053145879721395522091776566792268,
10 ^ 1 x 1.2499999999999999659868424472185766044029876359,
10 ^ 1 x 1.2500000000000000402493853651720306437850545540,
10 ^ 1 x 1.350000000000000004416996709974985823934933254642,
10 ^ 1 x 1.350000000000000004421443532537888105779619890527,
10 ^ 1 x 1.4500000000000000574246361810856479392430138234372,
10 ^ 1 x 1.4500000000000000574246384732497574527508867451697,
10 ^ 1 x 1.55000000000000061978957209295208731548251605838777,
10 ^ 1 x 1.55000000000000061978957209397995975329569117374561,
10 ^ 1 x 1.650000000005448810799042914329792294509710737528,
10 ^ 1 x 1.650000000005448810799042914734465413927060132512,
10 ^ 1 x 1.75000000038081268835369405683881030953392574759,
10 ^ 1 x 1.750000000380812688353694056840291039123740838877,
10 ^ 1 x 1.850000020507043780031864988451630954352408854039,
10 ^ 1 x 1.850000020507043780031864988451635333251853861565,
10 ^ 1 x 1.950000815867294501046405034523704915813165864541,
10 ^ 1 x 1.950000815867294501046405034523704928010408453453,
10 ^ 1 x 2.050022568018517034412527273640041808200744223750,
10 ^ 1 x 2.050022568018517034412527273640041808231370908819,
10 ^ 1 x 2.150395200266536132836611456811806949641606804821,
10 ^ 1 x 2.150395200266536132836611456811806949641675645570,
10 ^ 1 x 2.253894111930644088976740590263711884819586263287,
10 ^ 1 x 2.253894111930644088976740590263711884819586491979,
10 ^ 1 x 2.37106786473304648832769963393362026697201398322,
10 ^ 1 x 2.37106786473304648832769963393362026697201896063,
10 ^ 1 x 2.524619418290335757058688396767205574031125611895,
10 ^ 1 x 2.524619418290335757058688396767205574031125782293,

```

Example: Computing eigenvalues of order n using 40 and 60 digits

```

10 ^ -1 x -9.641321726904788469203807653558725272820102494785,
10 ^ -1 x 2.126628425131107295702128494459102204898454357475,
10 ^ 0 x 1.078164406734610586751527260933515250175346242597,
10 ^ 0 x 1.654730092254134485579766753257886141779285333348,
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10 ^ 0 x 5.500050238625574493614629202431453164635212134466,
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10 ^ 0 x 6.500001455954136799897192333983951377827078801077,
10 ^ 0 x 7.499999970478811371657446880312535145009630930559,
10 ^ 0 x 7.500000030730059526457051748353478345759432546457,
10 ^ 0 x 8.499999999521540927978771807129468065254241367295,
10 ^ 0 x 8.500000000493206277760349451609484527161829931395,
10 ^ 0 x 9.49999999993923902705172850882166649743950242226,
10 ^ 0 x 9.500000000006222657447847663151767192196337560297,
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10 ^ 1 x 1.7500000000380812688353694056840291039123740838877,
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10 ^ 1 x 1.850000020507043780031864988451635333251853861565,
10 ^ 1 x 1.950000815867294501046405034523704915813165864541,
10 ^ 1 x 1.950000815867294501046405034523704928010408453453,
10 ^ 1 x 2.050022568018517034412527273640041808200744223750,
10 ^ 1 x 2.050022568018517034412527273640041808231370908819,
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10 ^ 1 x 2.150395200266536132836611456811806949641675645507,
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10 ^ 1 x 2.253894111930644088976740590263711884819586491979,
10 ^ 1 x 2.371067864733304648832769963393362026697201398322,
10 ^ 1 x 2.371067864733304648832769963393362026697201896063,
10 ^ 1 x 2.524619418290335757058688396767205574031125611895,
10 ^ 1 x 2.524619418290335757058688396767205574031125782293,

```

```

10 ^ -1 x -9.641321726904788469203807653558725272820117108072431812438205,
10 ^ -1 x 2.126628425131107295702128494459102204898455201045349204017048,
10 ^ 0 x 1.078164406734610586751527260933515250175346019271672542088771,
10 ^ 0 x 1.654730092254134485579766753257886141779285140008442589285019,
10 ^ 0 x 2.400771751580549653471719453673745125831511857709953513876728,
10 ^ 0 x 2.613723558709657970251705419366973354981508439411334331604370,
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10 ^ 0 x 3.517639311060085206913357746819011821997392015649007013593949,
10 ^ 0 x 4.498968620932769352208565164016883576924323049729698939830236,
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10 ^ 0 x 7.499999970478811371657446880312535145009630113259921077898123,
10 ^ 0 x 7.500000030730059526457051748353478345759431690104142798319905,
10 ^ 0 x 8.499999999521540927978771807129468065254240939765221646674981,
10 ^ 0 x 8.500000000493206277760349451609484527161829486278766873006457,
10 ^ 0 x 9.49999999993923902705172850882166649743949997059140087143068,
10 ^ 0 x 9.500000000006222657447847663151767192196337327191821599661756,
10 ^ 1 x 1.04999999999993785719572185114285224895492382413128483720742,
10 ^ 1 x 1.050000000000006335023029689638865159736458990204293781960215,
10 ^ 1 x 1.14999999999999947691728926053358946623871022881269565924316,
10 ^ 1 x 1.150000000000000053145879721395522091776566748209216383720022,
10 ^ 1 x 1.24999999999999995986842447218576604402976793511970283586,
10 ^ 1 x 1.25000000000000000402493853651720306437850429139291844996199,
10 ^ 1 x 1.350000000000000000441699670997498582393493350683994156471134,
10 ^ 1 x 1.3500000000000000004421443532537888105779619989886566224028740,
10 ^ 1 x 1.45000000000000000574246361810856479392430138390795100672318024,
10 ^ 1 x 1.45000000000000000574246384732497574527508867610493494632607331,
10 ^ 1 x 1.55000000000000061978957209295208731548251605949790700285940995,
10 ^ 1 x 1.55000000000000061978957209397995975329569117484154113248419404,
10 ^ 1 x 1.650000000000544881079904291432979229450971076550330091746117,
10 ^ 1 x 1.6500000000005448810799042914734465413927060157126166124306207,
10 ^ 1 x 1.7500000000380812688353694056838881030953392375964320796572632,
10 ^ 1 x 1.750000000038081268835369405684029103912374064782277876662806,
10 ^ 1 x 1.850000020507043780031864988451630954352408930096037766099131,
10 ^ 1 x 1.850000020507043780031864988451635333251853935993717892930242,
10 ^ 1 x 1.950000815867294501046405034523704915813165780014921711917754,
10 ^ 1 x 1.950000815867294501046405034523704928010408367449461931580531,
10 ^ 1 x 2.050022568018517034412527273640041808200744365950473005838132,
10 ^ 1 x 2.050022568018517034412527273640041808231371048706371921123406,
10 ^ 1 x 2.150395200266536132836611456811806949641606957197298629818159,
10 ^ 1 x 2.1503952002665361328366114568118069496416757947763264619277,
10 ^ 1 x 2.253894111930644088976740590263711884819586224791692110944053,
10 ^ 1 x 2.253894111930644088976740590263711884819586347193253721016049,
10 ^ 1 x 2.371067864733304648832769963393362026697201890611963941496156,
10 ^ 1 x 2.37106786473330464883276996339336202669720189070644946616385,
10 ^ 1 x 2.524619418290335757058688396767205574031125780246667015958942,
10 ^ 1 x 2.524619418290335757058688396767205574031125780246674399808560,

```

Nonlinear Equations

Nonlinear Equations – finding “zeros” of

$$f(x) = 0$$

Common solvers:

- **PETSc** – e.g. Newton-Krylov method.
- **MINPACK**
- **TAO** – Toolkit for Advanced Optimization (Argonne).
- **Harwell** Subroutine Library (**HSL**) – A collection of state-of-the-art Fortran code for large scale scientific computing, developed by NAG and others.
- **IMSL**
- **NAG**

See also in PDEs later.

Example: Solving nonlinear equation using PETSc. For nonlinear equation

$$F(x) = 0, \quad x \in \mathbb{R}^n.$$

Let $x^{(i)}$ be the approximation and Δx a correction such that $F(x^{(i)} + \Delta x) = 0$. By Taylor expansion

$$F(x^{(i)} + \Delta x) = 0 = F(x^{(i)}) + F'(x^{(i)})\Delta x + O(\Delta x^2)$$

we have the **Newton** approximation

$$F'(x^{(i)})\Delta x = -F(x^{(i)}) \tag{1}$$

$$x^{(i+1)} = x^{(i)} + \Delta x \tag{2}$$

Eq. (1) is mostly solved using **Krylov** subspace method.

When solving PDEs, we often end up with a system of nonlinear equations.

Optimization

Optimization Problems

$$\min_x f(x), \quad \text{s.t. } g(x) = 0, \quad \text{and, } h(x) \leq 0.$$

Commonly used packages

- **APPSPACK (-> HOPSPACK)** – Asynchronous parallel pattern search with derivative free, by Sandia National Laboratory
- **GSL**
- **NAPACK**
- **MINPACK**
- **OPT++** – An OO nonlinear optimization library (Sandia).
- **TAO** – Toolkit for Advanced Optimization (Argonne).
- **HSL** (Harwell Subroutine Library)
- **IMSL**
- **NAG**

Example: Data fitting with nonlinear least squares

$$f(x; a, b, \lambda) = a \exp(-\lambda x) + b$$

to fit observation data y_i with uncertainty σ_i . The goal is to find parameters a , λ and b such that

$$\chi(a, b, \lambda)^2 = \sum_{i=1}^n \left(\frac{y_i - f(x_i; a, b, \lambda)}{\sigma_i} \right)^2.$$

Two methods are commonly used, both work well

- Levenberg-Marquardt – requires computing the derivatives.
- Nelder-Mead – simplex search method, does not require to compute derivative information.
- Both methods are available in GSL.

Example: Using derivatives

```
#include <stdlib.h>
#include <stdio.h>
#include <gsl/gsl_vector.h>
#include <gsl/gsl_blas.h>
#include <gsl/gsl_multifit_nlin.h>
#include "expfit.c"
#define N 40
void print_state (size_t iter, gsl_multifit_fdfsolver * s);

int main (void) {
    const gsl_multifit_fdfsolver_type *T;
    gsl_multifit_fdfsolver *s;
    int status; unsigned int i,
    iter = 0;
    const size_t n = N;
    const size_t p = 3;
    gsl_matrix *covar = gsl_matrix_alloc (p, p);
    double y[N], sigma[N];
    struct data d = { n, y, sigma};
    gsl_multifit_function_fdf f;
    double x_init[3] = { 1.0, 0.0, 0.0 };
    gsl_vector_view x = gsl_vector_view_array (x_init, p);
    const gsl_rng_type * type;
    gsl_rng * r;
    gsl_rng_env_setup();
    type = gsl_rng_default;
    r = gsl_rng_alloc (type);
```

```
f.f = &expb_f;
f.df = &expb_df;
f.fdf = &expb_fdf;
f.n = n;
f.p = p;
f.params = &d;
```

```
T = gsl_multifit_fdfsolver_lmsder;
s = gsl_multifit_fdfsolver_alloc (T, n, p);
gsl_multifit_fdfsolver_set (s, &f, &x.vector);
print_state (iter, s);
```

```
do {
    iter++;
    status = gsl_multifit_fdfsolver_iterate (s);
    printf ("status = %s\n",
    gsl_strerror (status));
    print_state (iter, s);
    if (status) break;
    status = gsl_multifit_test_delta (s->dx, s->x, 1e-4, 1e-4);
}
while (status == GSL_CONTINUE && iter < 500);
... ..
```

Example from GSL

Example: The use of Nelder-Mead simplex method to search the minimum

```
int main(void)
{
    double par[5] = {1.0, 2.0, 10.0, 20.0, 30.0};
    const gsl_multimin_fminimizer_type *T =
        gsl_multimin_fminimizer_nmsimplex2;
    gsl_multimin_fminimizer *s = NULL;
    gsl_vector *ss, *x;
    gsl_multimin_function minex_func;
    size_t iter = 0;
    int status; double size; /* Starting point */

    x = gsl_vector_alloc(2);
    gsl_vector_set(x, 0, 5.0);
    gsl_vector_set(x, 1, 7.0); /* Set initial step sizes to 1 */
    ss = gsl_vector_alloc(2);
    gsl_vector_set_all(ss, 1.0); /* Initialize method and iterate */

    minex_func.n = 2;
    minex_func.f = my_f;
    minex_func.params = par;
    s = gsl_multimin_fminimizer_alloc(T, 2);
    gsl_multimin_fminimizer_set(s, &minex_func, x, ss);
```

```
do {
    iter++;
    if (status = gsl_multimin_fminimizer_iterate(s)) break;
    size = gsl_multimin_fminimizer_size(s);
    status = gsl_multimin_test_size(size, 1e-2);
    if (status == GSL_SUCCESS) { printf("converged to minimum
        at\n"); }
    printf("%5d %10.3e %10.3e f() = %7.3f size = %.3f\n", iter,
        gsl_vector_get(s->x, 0), gsl_vector_get(s->x, 1), s->fval, size);
}
while (status == GSL_CONTINUE && iter < 100);
... ..
return status;
}
```

Example from GSL

Integration

Numerical Integration

$$I = \int \cdots \int_D f(x_1, \dots, x_n) dx_1 \cdots dx_n, \quad D \subseteq \mathbb{R}^n$$

Commonly use software packages

- **QUADPACK**
- **GSL** – Using QUADPACK (reimplemented) and Monte-Carlo based.
- **Cuba** – A library for multidimensional integrations on $[0, 1]^n$, containing
 - One unified interface to three Monte-Carlo based (Vegas, Suave, Divonne) using different sampling schemes, and one deterministic (Cohre) algorithms;
 - Written in C, has C/C++, Fortran and Mathematica interfaces;
 - Parallelization capable on multicore (shared memory) architecture.

See T. Hahn, “*Cuba: A library for multidimensional numerical integration*”, 2014.

- **IMSL**
- **NAG**
- **HSL**

Matlab

Example

```
I = dblquad(@(x,y) cos(4*x - 3*y + 2*pi), 0,1,0,1)
```

Via Cuba

! The calling routine

... ..

```
call cuba(method, ndim, ncomp, integrand, &
    integral, error, prob)
```

... ..

! User defined integrand f(x,...)

```
integer function integrand(ndim, xx, ncomp, f)
```

```
    implicit none
```

```
    integer ndim, ncomp
```

```
    double precision xx(*), ff(*)
```

```
    parameter (pi = 3.14159265358979323846D0)
```

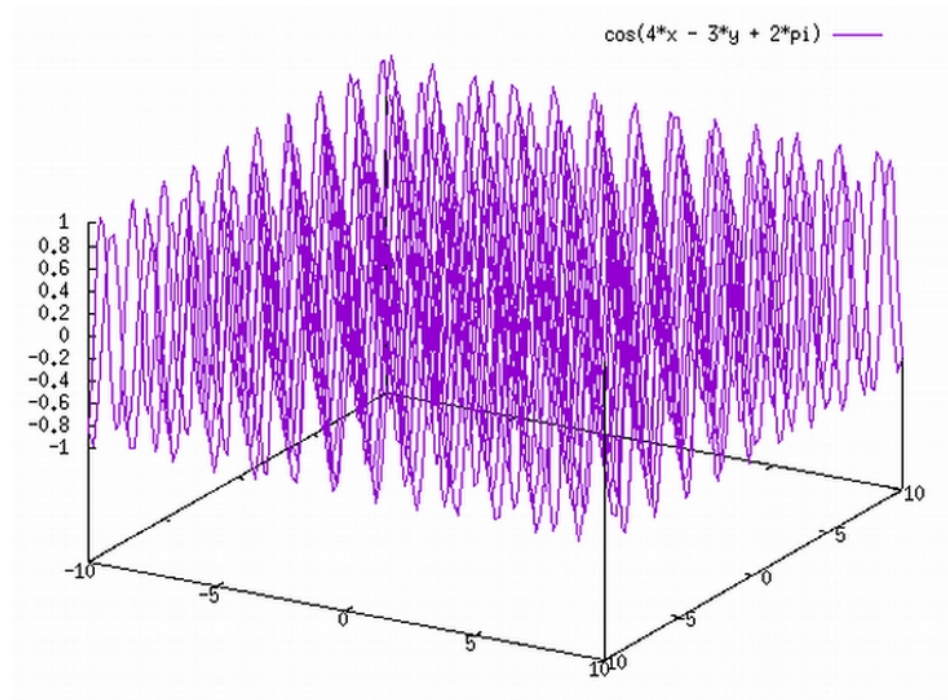
```
    x = xx(1)
```

```
    y = xx(2)
```

```
    f(1) = cos(4.0d0*x - 3.0d0*y + 2.0*pi)
```

```
    Integrand = 0
```

```
end function integrand
```



$$I = \int_0^1 \int_0^1 \cos(4x - 3y + 2\pi) dx dy$$

ODE Solvers

ODEs

$$\frac{dy}{dt} = f(t, y), \quad y(0) = y_0$$

Commonly used packages

- **odeint (Boost C++ Libraries)**
- **Intel ODE solvers**
- **SUNDIALS** – A suite of solvers, parallel processing ready.
- **ODELPACK**
- **GSL**
- **IMSL**
- **NAG**
- **HSL**

ODE solvers – functional components

- The **function** – to evaluate the right-hand-side $f(t,y)$
- The “**stepper**” – integration scheme, e.g. explicit, implicit methods
- The **Jacobian** of $f(t,y)$ – when implicit methods are employed, there might be a need to compute the Jacobian at each time step.

ODEs (cont'd)

▪ Boost.Numeric.Odeint

- C++ interface, simple and clean
- User to provide **RHS**, and **Jacobian** if necessary
- Contains a number of integration schemes – **steppers** (including **multistep** and **adaptive step control** schemes) – and also allow user to supply a stepper as well
- Can be used to solve stiff ODEs.

Lorenz system

$$\dot{x} = \sigma(y - x)$$

$$\dot{y} = Rx - y - xz$$

$$\dot{z} = -bz + xy$$

Example

```
#include <iostream>
#include <boost/array.hpp>
```

```
#include <boost/numeric/odeint.hpp>
```

```
using namespace std;
using namespace boost::numeric::odeint;
```

```
const double sigma = 10.0;
const double R = 28.0;
const double b = 8.0 / 3.0;
```

```
typedef boost::array< double , 3 > state_type;
```

```
void lorenz( const state_type &x , state_type &dxdt , double t )
{
    dxdt[0] = sigma * ( x[1] - x[0] );
    dxdt[1] = R * x[0] - x[1] - x[0] * x[2];
    dxdt[2] = -b * x[2] + x[0] * x[1];
}
```

```
void write_lorenz( const state_type &x , const double t )
{
    cout << t << '\t' << x[0] << '\t' << x[1] << '\t' << x[2] << endl;
}
```

```
int main(int argc, char **argv)
{
    state_type x = { 10.0 , 1.0 , 1.0 }; // initial conditions
    integrate( lorenz , x , 0.0 , 25.0 , 0.1 , write_lorenz );
}
```

ODEs (cont'd)

- Intel ODE solver (NOT part of MKL)
 - Fortran, C/C++ interfaces;
 - User to provide **RHS** and **Jacobian**;
 - Contains different **steppers**;
 - Considered effective for stiff ODEs.

```
void f(int *n, double *t, double *y, double *dydt)
{
    dydt[0] = -0.013*y[0] - 1000.0*y[0]*y[2];
    dydt[1] = -2500.0*y[1]*y[2];
    dydt[2] = -0.013*y[0] - 1000.0*y[0]*y[2] - 2055.0*y[1]*y[2];
}
```

```
void df(int *n, double *t, double *y, double *jac)
{
    jac[0] = -0.013 - 1000.0*y[2];
    jac[1] = 0.0;
    jac[2] = -0.013 - 1000.0*y[2];

    jac[3] = 0.0;
    jac[4] = -2500.0*y[2];
    jac[5] = -2055.0*y[2];

    jac[6] = -1000.0*y[0];
    jac[7] = -2500.0*y[1];
    jac[8] = -1000.0*y[0] - 2055.0*y[1];
}
```

```
#include <stdio.h>
#include "intel_ode.h"
```

```
int main(void)
{
    int n, ierr, i;
    int kd[3], ipar[128]; // Set ipar size to 128
    double t_0, t, t_end, h_0, h, hm, ep, tr;
    double y[3], dpar[39]; // dpart size: max{13*n,(7+2*n)*n}=max{39,39}=39

    for (i=0;i<128;i++) ipar[i]=0;
```

```
// Set initial conditions
```

```
read_data(&n, &t_0, &t_end, &h_0, &hm, &ep, &tr, y);
```

```
// Solve ODE using implicit solver, with output of intermediate values
```

```
t = t_0;
h = h_0;
printf("\nSolution repeated:\n");
printf("%g,%g,%g,%g,%g\n",t,h,y[0],y[1],y[3]);
```

```
do
```

```
{
```

```
    ipar[2] = 1; // To use Merson's multistep method
    ipar[3] = 1; // To exit after each step (for intermediate values)
    ipar[4] = 1; // To use provided Jacobian function
```

```
    dodesol_mk52lfn(
        ipar,&n,&t,&t_end,y, f, df, &h,&hm,&ep,&tr,dpar,kd,&ierr
    );
    printf("%g,%g,%g,%g,%g\n",t,h,y[0],y[1],y[3]);
```

```
}
```

```
while (t < t_end);
```

```
return 0;
```

```
}
```

A stiff problem

$$\begin{aligned}\dot{x} &= -0.013x - 1000xz, \\ \dot{y} &= -2500yz, \\ \dot{z} &= -0.013x - 1000xz - 2500yz.\end{aligned}$$

Example

SUNDIALS – A suite of nonlinear differential/algebraic solvers

- **CVODE** – solves initial value problems for ordinary differential equation (ODE) systems.
- **CVODES** – solves ODE systems and includes sensitivity analysis capabilities (forward and adjoint).
- **IDA** – solves initial value problems for differential-algebraic equation (DAE) systems.
- **IDAS** – solves DAE systems and includes sensitivity analysis capabilities (forward and adjoint).
- **KINSOL** – solves nonlinear algebraic systems.

<https://computation.llnl.gov/casc/sundials/main.html>

PDE Solvers

PDEs – closely related to the solution of linear systems, e.g. discretizing the equation

$$f(x, y, z, u_{xx}, u_{yy}, u_{zz}, u_{xy}, u_{yz}, u_{xz}, u_x, u_y, u_z) = 0$$

results in linear or nonlinear system of equations.

Commonly used packages

- **PETSc** – A popular toolkit, parallel processing ready. Works on nonlinear/linear systems often derived from numerical discretization of PDE or system of PDEs.
- **IMSL**
- **NAG**
- **Diffpack**
- **ANSYS**
- **COMSOL**
- **OpenFOAM**
-

Example: (Cont'd) Suppose we end up with a nonlinear system

$$F(x) = 0, \quad x \in \mathbb{R}^n.$$

Let $x^{(i)}$ denote the approximation of the discrete values of unknown function from the discretization of the PDE on a grid, we are to solve

$$F'(x^{(i)})\Delta x = -F(x^{(i)}), \quad (1)$$

$$x^{(i+1)} = x^{(i)} + \Delta x. \quad (2)$$

The linear system Eq. (1) is solved using **Krylov** subspace method.

We use PETSc to solve the nonlinear system. We need at the minimum the following storage and function evaluations:

- X – solution vector
- R – residual vector, containing $F(X)$
- J – the Jacobian $F'(X)$

Optionally PETSc lets users define

- Krylov method
- preconditioner

```

#include "petscsnes.h"

34: int main(int argc,char **argv)
35: {
36:     SNES      snes;    // nonlinear solver context
37:     KSP       ksp;     // linear solver context
38:     PC        pc;      // preconditioner context
39:     Vec       x,r;     // solution, residual vectors
40:     Mat       J;       // Jacobian matrix
42:     PetscInt  its;
43:     PetscMPIInt size,rank;
44:     PetscScalar pfive = .5,*xx;
45:     PetscTruth flg;
46:     AppCtx    user;    // user-defined work context
47:     IS        isglobal,islocal;

49:     PetscInitialize(&argc,&argv,(char *)0,help);
50:     MPI_Comm_size(PETSC_COMM_WORLD,&size);
51:     MPI_Comm_rank(PETSC_COMM_WORLD,&rank);

53:     // Create nonlinear solver context
56:     SNESCreate(PETSC_COMM_WORLD,&snes);

58:     // Create solutions objects
64:     VecCreate(PETSC_COMM_WORLD,&x);
65:     VecSetSizes(x,PETSC_DECIDE,2);
67:     VecDuplicate(x,&r);

69:     if (size > 1){
        Setup for distributed processing
79:     }

82:     // Create Jacobian matrix data structure
84:     MatCreate(PETSC_COMM_WORLD,&J);
85:     MatSetSizes(J,PETSC_DECIDE,PETSC_DECIDE,2,2);
86:     MatSetFromOptions(J);

88:     PetscOptionsHasName(PETSC_NULL,"-hard",&flg);
89:     if (!flg) {
93:         SNESSetFunction(snes,r,FormFunction1,&user);
98:         SNESSetJacobian(snes,J,J,FormJacobian1,PETSC_NULL);
99:     } else {
100:         if (size != 1)
            SETERRQ(1,"This case is a uniprocessor example only!");
101:         SNESSetFunction(snes,r,FormFunction2,PETSC_NULL);
102:         SNESSetJacobian(snes,J,J,FormJacobian2,PETSC_NULL);
103:     }

106:     // Customize nonlinear solver; set runtime options
113:     SNESGetKSP(snes,&ksp);
114:     KSPGetPC(ksp,&pc);
115:     PCSetType(pc,PCNONE);
116:     KSPSetTolerances(ksp,1.e-4,\
        PETSC_DEFAULT,PETSC_DEFAULT,20);

118:     // Set SNES/KSP/KSP/PC runtime options
        SNESSetFromOptions(snes);

```

Example

```

128: // Evaluate initial guess; then solve nonlinear system
130: if (!flg) {
131:     VecSet(x,pfive);
132: } else {
133:     VecGetArray(x,&xx);
134:     xx[0] = 2.0; xx[1] = 3.0;
135:     VecRestoreArray(x,&xx);
136: }

144: SNESolve(snes,PETSC_NULL,x);
145: SNESGetIterationNumber(snes,&its);
146: if (flg) {
147:     Vec f;
148:     VecView(x,PETSC_VIEWER_STDOUT_WORLD);
149:     SNESGetFunction(snes,&f,0,0);
150:     VecView(r,PETSC_VIEWER_STDOUT_WORLD);
151: }

153: PetscPrintf(PETSC_COMM_WORLD,"number of Newton
iterations = %D\n\n",its);

156: // Free work space
160: VecDestroy(x); VecDestroy(r);
161: MatDestroy(J); SNESDestroy(snes);
162: if (size > 1){
163:     VecDestroy(user.xloc);
164:     VecDestroy(user.rloc);
165:     VecScatterDestroy(user.scatter);
166: }
167: PetscFinalize();
168: return 0;
169: }

```

Example

Summary

- PETSc' uses the following key opaque objects:
 - **SNES** - Solver object;
 - **KSP** - KSP object;
 - **PC** - Preconditioning object;
- PETSc also defines opaque matrix and vector types. Need interface routines to set and get values.
- User to define the computational grid.
- User to define routines for evaluating the function $F(x)$ and Jacobian $F'(x)$ as **CALLBACK** functions installed in SNES object.
- The solving procedure is self contained in the call to **SNESolve()**.
- Built with parallel processing enabled.

FFT

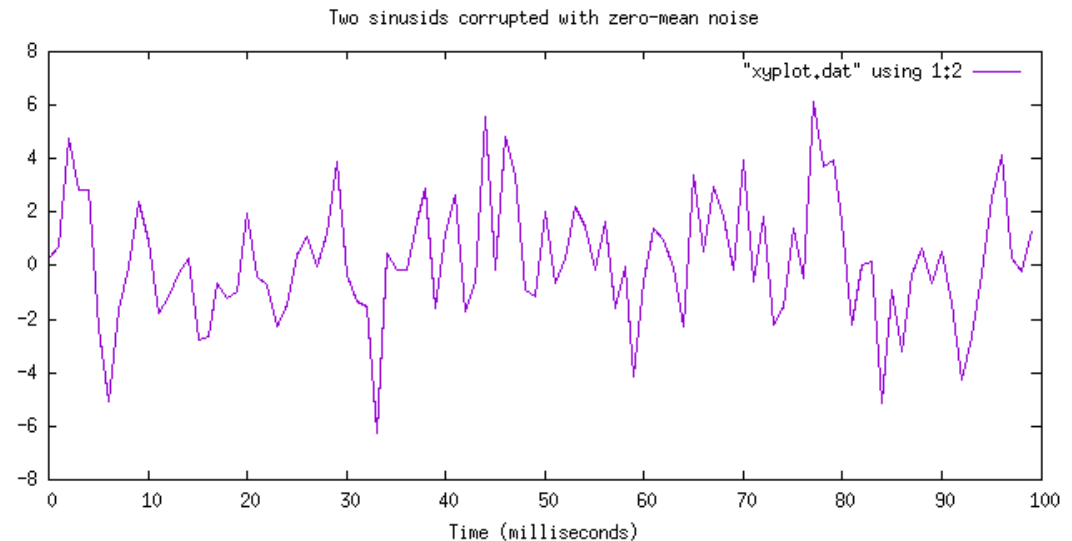
FFT – The best choice is ***FFTW***

- C/C++, Fortran interfaces;
- Used by Matlab, Octave, R, etc;
- For both serial and parallel processing – threaded and MPI.

Example – 1d signal processing via *FFTW*

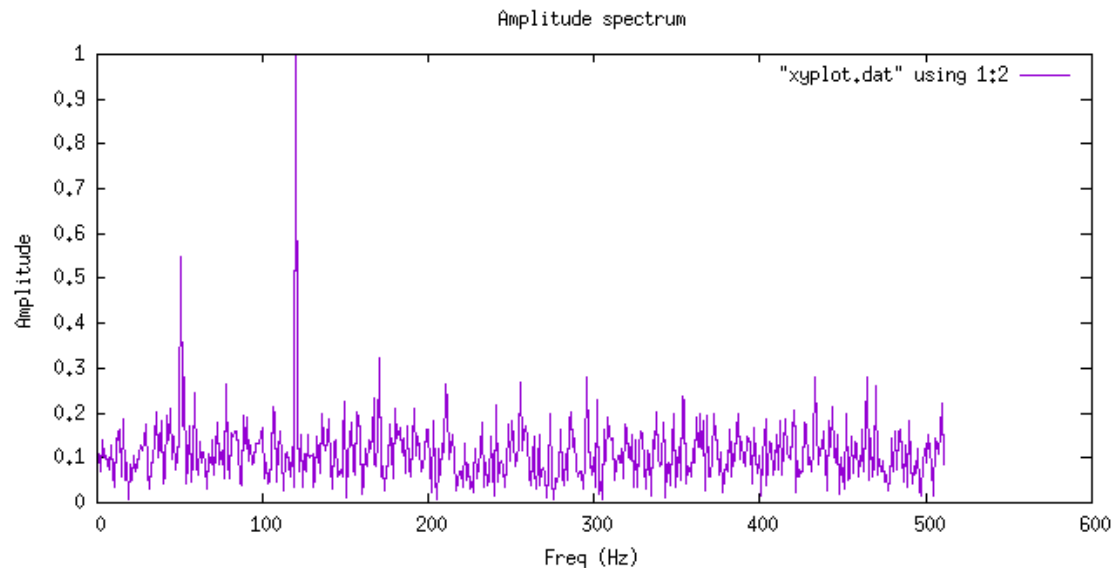
Input

$$x(t) = 0.7 \sin(2\pi 50t) + \sin(2\pi 120t) + r$$



Output

$$X(\omega) = FFT(x(t))$$



Matlab

```
Fs = 1000;           % Sampling frequency
T = 1/Fs;            % Sample time
L = 1000;            % Length of signal
t = (0:L-1)*T;       % Time vector
```

% Create signal vector: Two sinusoid corrupted by noise

```
x = 0.7*sin(2*pi*50*t) + sin(2*pi*120*t) + 2*randn(size(t));
figure(1)
plot(Fs*t(1:100),x(1:100))
title('Signal Corrupted with Zero-Mean Random Noise')
xlabel('time (milliseconds)')
input('Press ENTER key to continue');
```

% Performa FFT on vector x, output is y

```
NFFT = 2^nextpow2(L); % Next power of 2 from length of x
y = fft(x,NFFT)/L;
```

% Plot single-sided amplitude spectrum.

```
f = Fs/2*linspace(0,1,NFFT/2+1);
figure(2)
plot(f,2*abs(y(1:NFFT/2+1)))
title('Single-Sided Amplitude Spectrum of x(t)')
xlabel('Frequency (Hz)')
ylabel('|X(f)|')
input('Press ENTER key to continue');
```

Fortran

```
program fftw_signal
  use fftw
  use graphics
  implicit none
  integer, parameter :: dp=kind(1.0d0)
  real, parameter :: PI=3.14159265358979323846
  integer :: k = 1024      ! Sampling frequency
  real(dp) :: time        ! Sample time
  integer :: i, n = 1024   ! Length of signal
  real(dp) :: t(1024), f(1024), x(1024), noise(1024)
  complex(dp) :: y(1024)
  integer(8) :: plan
```

```
! Create time vector
time = 1.0/k
t = (/ (i,i=0,n-1)/ ) * time
```

! Create signal vector: Two sinusoids corrupted by noise

```
call randn(noise)
x = 0.7*sin(2*PI*50*t) + sin(2*PI*120*t) + 2*noise
call plot(k*t(1:100),x(1:100))
```

! Perform FFT on vector x, output is y

```
call dfftw_plan_dft_r2c_1d(plan, n, x, y, FFTW_ESTIMATE)
call dfftw_execute_dft_r2c(plan, x, y)
call dfftw_destroy_plan(plan)
y = y/k
```

```
! Create frequency vector
```

```
f = 0.5*k*/(i,i=0,n-1)//(n/2+1)
call plot(f,2*abs(y(1:n/2+1)),ymax=1.0d0,xlabel='Freq',ylabel='Amplitude')
end program fftw_signal
```

Example

FFTW functions

- `fftw_plan xfftw_plan_type_dim` (`fftw_plan plan`, `int n`, `fftw_dtype *in`, `fftw_dtype *out`, unsigned flag)
- `void xfftw_execute_type` (`fftw_plan plan`, `in`, `out`)
- `void xfftw_destroy_plan` (`fftw_plan plan`)

Example

- `dfftw_plan_dft_r2c_1d(plan, n, x, y, FFTW_ESTIMATE)`
- `dfftw_execute_dft_r2c(plan, x, y)` `FFTW_MEASURE`
- `dfftw_destroy(plan)` `FFTW_PATIENT`
- `...` `FFTW_EXHAUSTIVE`
- `dfftw_execute_dft_c2r(plan, x, y)` `FFTW_WIDSOM_ONLY`
- `...`

Random Number Generators

Random Number Generators

- **GSL** – has a collection of high quality RNGs:
 - 60+ RNGs;
 - 40+ distributions;
 - Easy to use, callable from C/C++ and Fortran.
- **SPRNG** – Scalable parallel random number generators library.
 - Work with MPI
 - Currently has uniform distribution only.
- **RANLIB** – Fortran/C libraries from netlib.
- **HSL**
- **IMSL**
- **NAG**

Example: Random number generation using GSL

- GSL includes a set of high quality RNGs, set by the call to **gsl_rng_alloc(type)**
- The usage of GSL RNGs is relatively simple, involving the following

```
#include <gsl/gsl_rng.h>           // GSL RNG headers
#include <gsl/gsl_randist.h>        // Different random number distributions
```

```
rng_h = gsl_rng_alloc(gsl_rng_mt19937); // E.g. to use the MT-19937 algorithm, default
```

```
gsl_rng_set(rng_h, seed);           // Set seed
```

```
r = gsl_rng_uniform(rng_h);          // Call to get the next random number
r = gsl_rng_uniform_pos(rng_h);      // Return a positive number
r = gsl_rng_uniform_int(rng_h, N);   // Return an integer between 0 and N-1
```

or

```
r = gsl_ran_poisson(rng_h,  $\lambda$ );    // Get the next random number
r = gsl_ran_gaussian(rng_h,  $\sigma$ );    // Get the next from Gaussian distribution with var=1.0
```

Example: Generating random numbers from Poisson distribution using GSL

```
#include <stdio.h>
#include <time.h>
#include <gsl/gsl_rng.h>
#include <gsl/gsl_randist.h>

const gsl_rng *rng_h;    /* global rand number generator */

int main (int argc, char *argv[]) {
    unsigned long seed;
    int i, k, n = 10;
    double lambda = 3.0;

    get the lambda from command line

    rng_h = gsl_rng_alloc(gsl_rng_mt19937);
    srand(time(NULL));      /* initialization for rand() */
    seed = rand();          /* returns a non-negative integer */
    gsl_rng_set (rng_h, seed); /* seed the RNG */

    for (i = 0; i < n; i++) {
        k = gsl_ran_poisson (rng_h, lambda);
        printf ("%u", k);
    }

    gsl_rng_free(rng_h);
    return 0;
}
```

Example: An Fortran implementation of randn() using GSL

```
subroutine randn(r)
    implicit none
    integer, parameter :: dp=kind(1.0d0)
    real(dp) :: r(:)
    integer :: n

    n = size(r)
    call crandn (n, r)
end subroutine randn
```

Fortran interface

```
#include <stdio.h>
#include <gsl/gsl_rng.h>
#include <gsl/gsl_randist.h>

double crandn_ (int *n, double *ra)
{
    int i;
    const gsl_rng_type * T;
    gsl_rng * r;

    gsl_rng_env_setup();
    T = gsl_rng_default;
    r = gsl_rng_alloc (T);

    for (i = 0; i < *n; i++)
        ra[i] = gsl_ran_gaussian(r, 1.0);
    gsl_rng_free (r);
}
```

C code

SPRNG: Some properties:

- Supports both serial and parallel programs.
- Several RNGs are employed. For instance, 48-bit linear congruential generator

$$x(n) = a * x(n-1) + p \% M$$

where a is a constant, p is a prime number and $M = 2^{48}$.

- It lets users to choose what to use via the call to
`init_sprng(seed, SPRNG_DEFAULT, rng_type)`
- It has all the serial RNGs' properties.
- It can generate multiple ***streams*** in parallel that are not correlated.
- Same “***seed***” – encoding of *starting state*, can generate distinct streams. This is convenient for users!
- Slightly different interfaces: serial vs. MPI and simple vs. default.
- Checkpoint capable.
- Unlike GSL, it does not come with functions for variety of distributions.

C++

```

#include <iostream>
#include <mpi.h>
#define SIMPLE_SPRNG
#define USE_MPI // use MPI to find number of processes
#include "sprng.h"
#define SEED 985456376
using namespace std;

int main(int argc, char *argv[]) {
    double rn; int i, myid; int gtype;

    MPI::Init(argc, argv); /* Initialize MPI */
    myid = MPI::COMM_WORLD.Get_rank();

    if(myid == 0) {
        #include "gen_types_menu.h"
        set rng;
    }
    MPI::COMM_WORLD.Bcast(&gtype,1,MPI::INT,0)
    init_sprng(SEED,SPRNG_DEFAULT,gtype);

    for (i=0;i<10000;i++) {
        rn = sprng();
        perform calculations
    }

    MPI::Finalize();
    return 0;
}

```

Fortran

```

program sprngf_mpi
    implicit none
    #define SIMPLE_SPRNG ! simple interface
    #define USE_MPI ! use MPI to find number of processes
    use mpi
    #include "sprng_f.h"
    SPRNG_POINTER:: junkPtr
    real(8):: rn
    integer:: seed, i, myid, ierr, junk, rng

    call MPI_INIT(ierr)
    call MPI_COMM_RANK(MPI_COMM_WORLD, myid, ierr)
    seed = 985456376

    if (myid .eq. 0) then
        #include "genf_types_menu.h"
        set rng
    endif
    call MPI_BCAST(rng, 1, MPI_INTEGER,0,MPI_COMM_WORLD,ierr)
    junkPtr = init_sprng(seed,SPRNG_DEFAULT,rng)

    do i = 1, 10000
        rn = sprng()
        perform calculations
    enddo
    call MPI_FINALIZE(ierr)
end program sprngf_mpi

```

Multipurpose Libraries

AMD Core Math Library (ACML)

- BLAS
- LAPACK
- FFT
- Random number generators

Fortran, C APIs

Intel Math Kernel Library (MKL)

- BLAS
- Sparse BLAS
- LAPACK
- ScaLAPACK
- Extended eigensolvers
- Direct and **Iterative Sparse Solver routines**
- **Vector Mathematical Library (VML) functions**
- **Vector Statistical Library (VSL) functions**
- FFT
- PDE solvers.
- **Optimization** solver routines for solving nonlinear least squares problems through the Trust-Region (TR) algorithms and computing Jacobi matrix by central differences
- **Data fitting**, differentiation and integration, and search
- GMP arithmetic functions

Fortran, C APIs

International Mathematical Software Library (IMSL)

▪ *Mathematics*

- Linear algebra
- Eigensystems
- **Interpolation and approximation**
- **Integration and differentiation**
- Differential equations
- Transforms
- **Optimizations**
- Nonlinear equations
- Vector, matrix operations
- Basic linear algebraic operations
- Utilities
- Parallel processing on distributed systems

▪ *Statistics*

- Basic stats
- Regression
- Correlations
- Analysis of variance
- Categorical and discrete data analysis
- Nonparametric stats
- Test of goodness of fit and randomness
- Time series analysis and forecasting
- Covariance structure and factor analysis
- Discriminant analysis
- Cluster analysis
- Sampling
- Survival analysis
- Multidimensional scaling
- Density and hazard estimation
- Line printer graphics
- Probability distribution functions and inverses
- Random number generation

▪ *Special Functions*

Fortran, C/C++ and other language APIs

Numerical Algorithms Group (NAG) Library

Numerical Libraries

- **Optimization**
- Linear, quadratic, integer and nonlinear programming and least squares problems
- ODEs, PDEs and mesh generation
- Solution of dense, banded and sparse linear equations and eigenvalue problems
- Linear and nonlinear least squares problems
- Curve and surface fitting and interpolation
- **Special functions**
- Numerical integration and integral equations
- Nonlinear equations
- **Option pricing formulae**
- **Wavelet Transforms**

Statistics Libraries

- Random number generation
- Simple calculations on statistical data
- Correlation and regression analysis
- Multivariate methods
- Analysis of variance and contingency table analysis
- Time series analysis
- Nonparametric statistics

Fortran, C APIs

GNU Scientific Library (GSL) – A collection of bit of everything...

- **Complex Numbers**
- Special Functions
- Permutations
- **Random Numbers**
- Quasi-Random Sequences
- Random Distributions
- Statistics
- Monte Carlo
- Simulated Annealing
- Series Acceleration
- Minimization
- Least-Squares Fitting
- Physical Constants
- Discrete Wavelet Transforms
- Roots of Polynomials
- **Vectors and Matrices**
- Sorting
- Linear Algebra
- Fast Fourier Transforms
- Transforms
- Interpolation and Approximations
- Numerical Differentiation
- Quadratures and Integration
- Differential Equations
- Root-Finding

C/C++ only!

Resources at *netlib* – A collection of packages

■ Key packages

- LINPACK
- EISPACK
- BLAS
- LAPACK
- ScaLAPACK
- MINPACK
- NAPACK
- MPFUN

■ Many other packages

<http://www.netlib.org/>

PETSc – Portable, Extensible Toolkit for Scientific Computing

- Vector, matrix objects and operations
- Finite difference approximation of Jacobians
- Linear system (dense and sparse) solvers: **LU** and Krylov subspace method with preconditioners (**KSP**).
- Nonlinear equation solvers (**SNES**).
- Time stepping (TS) solvers for ODEs.
- Eigenvalue problems with **SLEPc**.

<http://www.mcs.anl.gov/petsc/>

C/C++ and Fortran interfaces

Evident traces of C/C++ thinking

Works for multiprocessor environment, transparent to users

Error messages hard to comprehend

PETSc 3.1 – A list of packages needed...

Setting up libbtf1.1.0 (1:3.4.0-2ubuntu2) ... Setting up libcspars2.2.3 (1:3.4.0-2ubuntu2) ... Setting up libklu1.1.0 (1:3.4.0-2ubuntu2) ... Setting up libldl2.0.1 (1:3.4.0-2ubuntu2) ... Setting up libsuitesparse-dev (1:3.4.0-2ubuntu2) ... Setting up libsuperlu3 (3.0+20070106-3) ... Setting up libsuperlu3-dev (3.0+20070106-3) ... Setting up mpi-default-bin (0.6) ... Setting up libblacs-mpi1 (1.1-28.2build1) ... Setting up mpi-default-dev (0.6) ... Setting up libblacs-mpi-dev (1.1-28.2build1) ... Setting up libhdf5-openmpi-dev (1.8.4-patch1-2ubuntu3) ... Setting up libhdf5-mpi-dev (1.8.4-patch1-2ubuntu3) ...	Setting up libhypre-2.4.0 (2.4.0b-7) ... Setting up libhypre-dev (2.4.0b-7) ... Setting up libscalapack-mpi1 (1.8.0-6) ... Setting up libmumps-4.9.2 (4.9.2.dfsg-6) ... Setting up libscalapack-mpi-dev (1.8.0-6) ... Setting up libmumps-dev (4.9.2.dfsg-6) ... Setting up libscotch-5.1 (5.1.11.dfsg-7) ... Setting up libspooles2.2 (2.2-8) ... Setting up libpetsc3.1 (3.1.dfsg-10ubuntu1) ... Setting up libspooles-dev (2.2-8) ... Setting up libscotch-dev (5.1.11.dfsg-7) ... Setting up libpetsc3.1-dev (3.1.dfsg-10ubuntu1) ... update-alternatives: using /usr/lib/petscdir/3.1 to provide /usr/lib/petsc (petsc) in auto mode. update-alternatives: using /usr/lib/petscdir/3.1/aclocal/math-blaslapack.m4 to provide /usr/share/aclocal/math-blaslapack.m4 (math-blaslapack.m4) in auto mode. Setting up petsc-dev (3.1.dfsg-10ubuntu1) ...
--	---

Hypre – A library for solving large, sparse linear systems

- Common **Krylov** subspace based methods.
- Contains a suite of **preconditioners**.
- Uses MPI.

<http://acts.nersc.gov/hypre/>

Further Readings

- Netlib, <http://www.netlib.org/>.
- M. T. Heath, “*Scientific Computing: An introductory survey*”, 2nd Ed, 2002.
- Victor Eijkhout, “Overview of Iterative Linear System Solver Packages”, 1998.
- BLAS Quick References.
- LAPACK Quick References.
- LAPACK User’s Guide.
- ScaLAPACK User’s Guide.
- PETSc, <http://www.mcs.anl.gov/petsc/>. In active development, referencing to classic and recent literatures.
- GNU Scientific Libraries, <http://www.gnu.org/manual/manual.html>.
- Boost C++ libraries, http://www.boost.org/doc/libs/1_57_0/.
- Hardware vendor’s sites: AMD, Intel, HP, IBM, Sun, nVIDIA, etc.
- Software vendor’s sites: Intel, IMSL (Rogue Waves), NAG, etc.

Q&A