

# High Performance Computing with Python

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# Outline

- ▶ Speeding up Python code with NumPy
- ▶ Speeding up Python code with Cython
- ▶ Using MPI with Python, via mpi4py

Please attend our Summer School (next one held May 25-29, 2015) for more in depth coverage of this material.

# What is Python?

- ▶ Python is a programming language that appeared in 1991
- ▶ compare with Fortran (1957), C (1972), C++ (1983),
- ▶ While the older languages still dominate High Performance Computing (HPC), popularity of Python is growing

# Python advantages

- ▶ Designed from the start for better code readability
- ▶ Allows expression of concepts in fewer lines of code
- ▶ Has dynamic type system, variables do not have to be declared
- ▶ Has automatic memory management
- ▶ Has large number of easily accessible, extensive libraries (eg. NumPy, SciPy)
- ▶ All this makes developing new codes easier

## Python disadvantages

- ▶ Python is generally slower than compiled languages like C, C++ and Fortran
- ▶ Complex technical causes include dynamic typing and the fact that Python is interpreted, not compiled
- ▶ This does not matter much for a small desktop program that runs quickly.
- ▶ However, this will matter a lot in a High Performance Computing environment.
- ▶ Python use in HPC parallel environments is relatively recent, hence parallel techniques less well known
- ▶ Rest of this talk will describe approaches to ensure your Python code runs reasonably fast and in parallel

# 1D diffusion equation

To describe the dynamics of some quantity  $u(x,t)$  (eg. heat) undergoing diffusion, use:

$$\frac{\partial u}{\partial t} = \kappa \frac{\partial^2 u}{\partial x^2}$$

Problem: given some initial condition  $u(x,t=0)$ , determine time evolution of  $u$  and obtain  $u(x,t)$

Use finite difference with Euler method for time evolution

$$u(i\Delta x, (m+1)\Delta t) = u(i\Delta x, m\Delta t) + \frac{\kappa\Delta t}{\Delta x^2} \left[ u((i+1)\Delta x, m\Delta t) + u((i-1)\Delta x, m\Delta t) - 2u(i\Delta x, m\Delta t) \right]$$

## C code

```
1 #include <math.h>
2 #include <stdio.h>
3
4 int main(){
5
6     int const n=100000, niter=500;
7
8     double x[n], u[n], udt[n];
9     int i, iter;
10    double dx=1.0;
11    double kappa=0.1;
12
13    for (i=0; i<n; i++){
14        u[i]=exp(-pow(dx*(i-n/2.0), 2.0)/100000.0);
15        udt[i]=0.0;
16    }
17
18    ...
```

## C code continued :

```
1 ...
2 for (iter=0;iter<niter;iter++){
3     for (i=1;i<n-1;i++){
4         udt[i]=u[i]+kappa*(u[i+1]+u[i-1]-2*u[i]);
5     }
6     for (i=0;i<n;i++){
7         u[i]=udt[i];
8     }
9 }
10 return 0;
11 }
```



## Program output

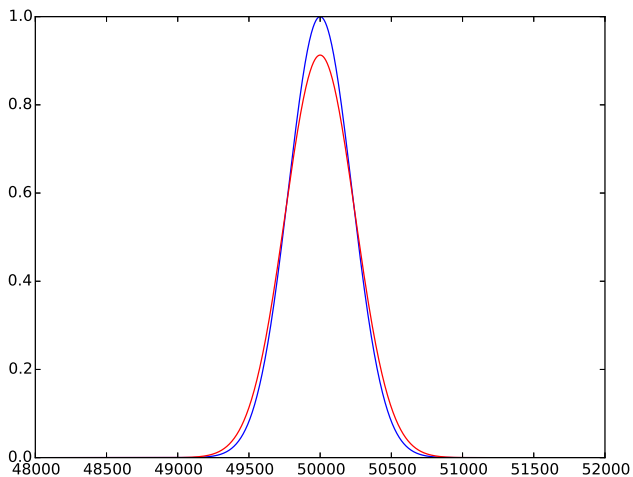


Figure: Evolution of  $u(x)$  after 50,000 time steps (blue line initial, red line final)

# NumPy

- ▶ To implement the same in Python, will need support for efficient, large numerical arrays
- ▶ These provided by NumPy, an extension to Python
- ▶ NumPy (<http://www.numpy.org/>) along with SciPy (<http://www.scipy.org/>) provide a large set of easily accessible libraries which make Python so attractive to the scientific community

## "Vanilla" Python code

```
1 import numpy as np
2 n=100000 ; dx=1.0 ; niter=500 ; kappa=0.1
3 x=np.arange(n,dtype="float64")
4 u=np.empty(n,dtype="float64")
5 udt=np.empty(n,dtype="float64")
6
7 for i in xrange(len(u)):
8     u[i]=np.exp(-(dx*(i-n/2))**2/100000)
9
10 udt[:]=0.0
11
12 for i in xrange(niter):
13
14     for i in xrange(1,n-1):
15         udt[i]=fac*u[i]+kappa*(u[i+1]+u[i-1]-2*u[i])
16
17     for i in xrange(len(u)):
18         u[i]=udt[i]
```

## Vanilla code performance

- ▶ 500 iterations, tested on Macbook Pro laptop (2011)
- ▶ C code compiled with GCC takes 0.21 seconds
- ▶ Python "vanilla" code takes 64.75 seconds
- ▶ Python is much slower (by factor 308)
- ▶ Even though we are using Python arrays, code is slow because loops are explicit
- ▶ Must use NumPy array operations instead
- ▶ The difficulty of eliminating loops varies.

## Slicing NumPy arrays :

```
1 sharcnet1:~ pawelpomorski$ python
2 Python 2.7.9 (default, Dec 12 2014, 12:40:21)
3 [GCC 4.2.1 Compatible Apple LLVM 6.0 (clang-600.0.56)]
   on darwin
4 Type "help", "copyright", "credits" or "license" for
   more information.
5 >>> import numpy as np
6 >>> a=np.arange(10)
7 >>> a
8 array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
9 >>> a[1:-1]
10 array([1, 2, 3, 4, 5, 6, 7, 8])
11 >>> a[0:-2]
12 array([0, 1, 2, 3, 4, 5, 6, 7])
13 >>> a[1:-1]+a[0:-2]
14 array([ 1,  3,  5,  7,  9, 11, 13, 15])
15 >>>
```

## NumPy vector operations

### Replace explicit loops

```
1 for i in xrange(1, n-1):  
2     udt[i] = fac * u[i] + kappa * (u[i+1] + u[i-1] - 2 * u[i])
```

with NumPy vector operations using slicing

```
1 udt[1:-1] = u[1:-1] + kappa * (u[0:-2] + u[2:] - 2 * u[1:-1])
```

## Python code using Numpy operations instead of loops

```
1
2 import numpy as np
3
4 n=100000; dx=1.0; niter=50000; kappa=0.1
5
6 x=np.arange(n, dtype="float64")
7 u=np.empty(n, dtype="float64")
8 udt=np.empty(n, dtype="float64")
9
10 u_init = lambda x: np.exp( -(dx*(x-n/2))**2/100000)
11 u=u_init(x)
12 udt[:]=0.0
13
14 for i in xrange(niter):
15     udt[1:-1]=u[1:-1]+kappa*(u[0:-2]+u[2:]-2*u[1:-1])
16     u[:]=udt[:]
```

# Performance

- ▶ 50,000 iterations, tested on Macbook Pro laptop (2011)
- ▶ C code compiled with `gcc -O2` - 12.75 s
- ▶ C code compiled with `gcc` (unoptimized) - 34.31 s
- ▶ Python code with NumPy operations - 40.43 s
- ▶ Python 3.2 times slower than optimized code, only 1.2 times slower than unoptimized code
- ▶ It's likely that GCC can optimize the whole loop over iterations, whereas Numpy vector operations optimize each iteration individually



# General approaches for code speedup

- ▶ NumPy does not help with all problems, some don't fit array operations
- ▶ Need a more general technique to speed up Python code
- ▶ As the problem is that Python is not a compiled language, one can try to compile it
- ▶ General compiler: `nuitka` (<http://nuitka.net/>) under active development
- ▶ PyPy (<http://pypy.org/>) - Just-in-Time (JIT) compiler
- ▶ **Cython** (<http://cython.org/>)- turns Python program into C and compiles it

## Euler problem

If  $p$  is the perimeter of a right angle triangle with integral length sides,  $a, b, c$ , there are exactly three solutions for  $p = 120$ .

$(20, 48, 52)$ ,  $(24, 45, 51)$ ,  $(30, 40, 50)$

For which value of  $p < N$ , is the number of solutions maximized?  
Take  $N=1000$  as starting point

(from <https://projecteuler.net> )

## Get solutions at particular p

```
1 def find_num_solutions(p):
2     n=0
3     # a+b+c=p
4     for a in range(1,p/2):
5         for b in range(a,p):
6
7             c=p-a-b
8             if(c>0):
9                 if(a*a+b*b==c*c):
10                    n=n+1
11
12     return n
```

Loop over possible value of p up to N

```
1 nmax=0 ; imax=0
2 N=1000
3
4 for i in range(1,N):
5     print i
6     nsols=find_num_solutions(i)
7     if(nsols>nmax):
8         nmax=nsols ; imax=i
9
10 print "maximum p , number of solutions" ,imax ,nmax
```

# Cython

- ▶ The goal is to identify functions in the code where it spends the most time
- ▶ Place those functions in a separate file so they are imported as module
- ▶ Cython will take a python module file, convert it into C code, and then compile it into a shared library
- ▶ Python will import that compiled library module at runtime just like it would import a standard Python module
- ▶ To make Cython work well, need to provide some hints to the compiler as to what the variables are, by defining some key variables

## Invoking Cython

- ▶ Place module code (with Cython modifications) in `find_num_solutions.pyx`
- ▶ Create file `setup.py`

```
1 from distutils.core import setup
2 from Cython.Build import cythonize
3
4 setup(
5     ext_modules=cythonize("find_num_solutions.pyx"),
6 )
```

- ▶ Execute: `python setup.py build_ext -inplace`
- ▶ Creates `find_num_solutions.c`, C code implementation of the module
- ▶ From this creates `find_num_solutions.so` library which can be imported as Python module at runtime

## Get solutions at particular p, cythonized

```
1 def find_num_solutions(int p): # note definition
2     cdef int a,b,c,n         # note definition
3     n=0
4 # a+b+c=p
5     for a in range(1,p/2):
6         for b in range(a,p):
7
8             c=p-a-b
9
10            if(c>0):
11                if(a*a+b*b==c*c):
12                    n=n+1
13
14    return n
```

This code in file find\_num\_solutions.pyx

Loop over possible value of  $p$  up to  $N$ , with Cython

Note changes at line 1 and line 9

```
1 import find_num_solutions
2
3 nmax=0 ; imax=0 ; N=1000
4
5 for i in range(1,N):
6     print i
7     nsols=find_num_solutions.find_num_solutions(i)
8     if(nsols>nmax):
9         nmax=nsols ; imax=i
10
11 print "maximum p and , number of solutions",imax,nmax
```



# Speedup with Cython

For  $N=1000$ , tested on development node of orca cluster

- ▶ vanilla python : 38.324 s
- ▶ Cython without variable definitions : 26.18 s, speedup factor 1.5
- ▶ Cython with integer variables defined : 0.416 s, speedup factor 92

# Parallelizing Python

- ▶ One the serial version is optimized, need to parallelize Python to do true HPC
- ▶ Threading approach does not work due to Global Interpreter Lock
- ▶ In Python, you can have many threads, but only one executes at any one time, hence no speedup
- ▶ Have to use multiple processes instead

# MPI - Message Passing Interface

- ▶ Approach has multiple processors with independent memory running in parallel
- ▶ Since memory is not shared, data is exchanged via calls to MPI routines
- ▶ Each process runs same code, but can identify itself in the process set and execute code differently

## Compare MPI in C and Python with mpi4py - MPI reduce

```
1 int main(int argc, char* argv[]) {
2     int my_rank, imax, imax_in;
3     MPI_Init(&argc, &argv);
4     MPI_Comm_rank(MPI_COMM_WORLD, &my_rank);
5     imax_in=my_rank;
6     MPI_Reduce(&imax_in, &imax, 1, MPI_INT, MPI_MAX, 0,
7     MPI_COMM_WORLD);
8     if (my_rank == 0) printf("%d \n", imax);
9     MPI_Finalize();
10    return 0;}
```

```
1 from mpi4py import MPI
2 comm = MPI.COMM_WORLD
3 myid = comm.Get_rank()
4 imax_in = myid
5 imax = comm.reduce(imax_in, op=MPI.MAX)
6 if (myid==0):
7     print imax
8 MPI.Finalize
```

## Loop over p values up to N distributed among MPI processes

```
1 from mpi4py import MPI
2 import find_num_solutions
3
4 comm = MPI.COMM_WORLD
5 myid = comm.Get_rank()
6 nprocs = comm.Get_size()
7
8 nmax=0 ; imax=0 ; N=5000
9
10 for i in range(1,N):
11
12     if (i%nprocs==myid):
13         nsols=find_num_solutions.find_num_solutions(i)
14         if (nsols>nmax):
15             nmax=nsols ; imax=i
16
17 imax_global=comm.reduce(imax,op=MPI.MAX)
18 MPI.Finalize
19
20 if (myid == 0) :
21     print "maximum p ",imax_global
```

# MPI performance

timing on orca development node (24 cores)

n=5000 case

MPI processes	time(s)	speedup
1	34.32	1.0
2	18.43	1.86
4	9.88	3.47
8	5.78	5.93
16	3.80	9.03
24	3.63	9.45

Will scale better for larger values of N

# Conclusion

- ▶ Python is generally slower than compiled languages like C
- ▶ With a bit of effort, can take a Python code which is a great deal slower and make it only somewhat slower
- ▶ The tradeoff between slower code but faster development time is something the programmer has to decide
- ▶ Tools currently under development should make this problem less severe over time