

# Quick-n-dirty ways to run your serial code faster, in parallel

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# Foreword

- This talk is **not** about optimizing / profiling a serial code (compiler optimization flags etc.)
- Instead, this talk is about accelerating the computations by running your serial code in parallel.
- Only the simplest parallelization techniques are considered; as a result, this will work well only for some codes and problems.

# Parallel computing primer



# What is a parallel code?

- A code is parallel when it consists of multiple processes running at the same time on multiple compute resources (CPU or GPU cores).
- Optionally there may be a need for data exchange (“communication”) between the processes, often requiring synchronization between processes.
  - When no data exchange is needed, we have an “embarrassingly parallel” case – or serial farming

# Memory

- Memory-wise, two situations exist:
  - When every process can access any byte of the memory (“global address space”, “global memory”), we have a “**shared memory**” situation.
    - On a single cluster node
    - “Device memory” on GPU
  - If this is not the case, we have a “**distributed memory**” situation.
    - Between cluster nodes
    - Between CPU and GPU



# Programming models

- At a low level, three basic programming models are in common use:
  - Distributed memory model (MPI)
  - Shared memory model (threads)
  - GPU model (CUDA/OpenCL) – actually a special case; a combination of distributed and shared memory models (+ vector computing)
- In the rest of the talk, only higher level approaches will be discussed; they are using the above low level models under the hood.

# Is parallel computing hard?

- There are many myths regarding parallel computing, e.g.:
  - Only “hard core” parallelization (converting a serial code to MPI / CUDA / pthreads) is the true one
    - Much simpler approaches considered here result in “true” parallel codes, albeit less efficient in some cases
  - It takes many months or even years to parallelize a large serial code
    - With the approaches considered here a conversion would probably take less than a day



# Caveats

- In a shared supercomputing resources environment (SHARCNET), running your code in parallel needs to be justified
  - It takes longer to wait for N cores than to wait for a single core, so if the speedup is not great, the total time (queuing + running) can become larger for the parallel version of the code.
- Also, very low parallel code efficiency is a waste of resources
  - A rule of thumb: running on N CPU cores, the speedup should be at least  $0.7 \times N$
  - For GPUs, the speedup should be at least  $\sim 10x$ .

# Theory

- Using a parallel code on the same size problem as the serial code usually results in low efficiency (speedup)
  - So-called Amdahl's law, or “strong scaling”
- The solution: use the parallel code on a larger size problem (more grid elements; more particles; more Monte Carlo steps; etc.)
  - Gustafson's law (“weak scaling”)
- Serial farming does not suffer from these issues



# Running your code in parallel

## Serial farming

# Definition

- Serial farming: running multiple copies of a serial code on multiple CPU cores at the same time.
- In the simplest case, there are no data dependencies
  - Meaning the final result does not depend on the order of execution of the serial jobs.
- In more complex cases, there may be dependencies between groups of serial jobs.
  - E.g., don't start group 2 until all the jobs in group 1 are finished.
  - This can be handled by using inter-job dependency features of the scheduler:

`sqsub --waitfor=jobid[,jobid...]`



# Myths vs. reality

- “Serial farming is not parallel computing”: myth. See the definition of a parallel code.
- “One should avoid using serial farming, because it is embarrassingly parallel”: myth.
  - Due to zero overhead (no communications), serial farming should rather be called “perfectly parallel”.
    - That is, when running on  $N$  cpu cores, the speedup is  $N$  (100% efficiency).
  - Also, the queuing time for say 128 serial farm jobs is much shorter on average than for a “true” 128-way parallel job.

# Typical applications

- Monte-Carlo type simulations
  - There is an implicit data dependency here: to make sure that all serial jobs are using unique random number sequences.
  - This is not an impediment, and can be easily handled (see the tutorial “Serial farming and Monte Carlo for SHARCNET” on SHARCNET's Help Wiki).
- Model parameter study
  - Model input parameters are often not precisely known, so one has to run a set of simulations with the parameters varying within the acceptable range.



# Implementation

- One can use any scripting language (bash, perl, python, ...) to write serial farm scripts – for job submission, queries, killing, post-processing.
- This bash script handles the common situation when a serial code has to run with a set of parameters, stored one line per job in a file:

```
while read line
do
    sqsub -o out%J -r 7d ./code "$line" | cut -d" " -f4 >> jobid
done < input_parameters.dat
```

Then the whole job batch can be killed with

```
sqkill `cat jobid`
```

Running your code in parallel

Using pagecache to accelerate I/O bound code



# Definition

- I/O bound code is the one where most of run time is spent in reading from and/or writing to the disk.
  - Such codes waste lots of CPU cycles, and can overload our file systems (making it very slow for everyone).
  - This is especially true if these jobs are run as a serial farm, on random nodes.
- But: if multiple processes read the same data and run on the same node, the Linux feature **pagecache** can dramatically accelerate computations.
- No changes to the code needed!

# Pagecache

- Pagecache is the cache of recent reads and writes, occupying all the unused memory in a node. It is operated by the Linux kernel.
- As long as there is enough of unused RAM to fit all the data which are being read, the reading from the disk only occurs once; all other code instances will get the data from the memory cache, which is dramatically faster.
- Serial farm using the pagecache feature is essentially a single multi-threaded parallel application, so one has to use the threaded queue to submit such jobs, e.g.:

```
sqsub -q threaded -n 24 -o out ./job_script.sh
```

Here job\_script.sh is a script launching 24 instances of the serial code (see next slide).



# Details

- `for ((i=0; i<24; i++)); do ./code [args] & done`  
`wait`
- Caveat: asking for many cores on a single node can result in a substantial queue wait time
  - True for any multi-threaded application
- For a code reading extremely large amounts of data, iqaluk is the best system to use
  - Only 32 cores, but 1TB of RAM; currently no scheduler
- Success story: one group (climate modelling; 50,000 serial jobs, each one reading 1 TB of the same data) got their results 25x faster, by switching from serial farm on random orca nodes to using iqaluk.

Running your code in parallel

Automatic code parallelization



# Compiler based parallelization

- Modern compilers can optionally compile your serial code as a parallel (multi-threaded) code, in a fully automatic fashion.
- Specifically, our intel compilers need `-parallel` option to carry out auto-parallelization:

```
icc -O3 -parallel code.c  
ifort -O3 -parallel code.f90
```

- Code compiled in this fashion is a “true” multi-threaded application, and needs to be submitted to the threaded queue, e.g.:

```
sqsub -q threaded -n 24 -o out -r 3d ./code
```

# Details

- When running the code interactively (on a development node), one can choose the number of threads to use by assigning a value to this environment variable:

```
export OMP_NUM_THREADS=24
```

- Parallelization only targets loops, with no data dependencies, and the number of iteration known at compile time.
- **-guide-par**, used in conjunction with **-parallel**, causes the compiler to generate advisory messages suggesting ways the programmer might help the compiler to auto-parallelize suitable loops. No object file is generated.



Running your code in parallel

Semi-automatic parallelization: OpenMP

# Preamble

- Fully automatic parallelization is too limited to be effective for most codes. Programmer can achieve significantly better results by guiding the parallelizing process.
- On CPU cores, the standard approach for semi-automatic parallelization is OpenMP.
- OpenMP does require some modifications to the code, but unlike “hard-core” approaches (MPI, pthreads, CUDA), OpenMP allows for *incremental parallelism* (the modified code still can be compiled and used as a serial code).



# Simplest case

- OpenMP supports a wide range of parallel programming tools, but we will only consider the simplest – loop parallelization:

```
#pragma omp parallel for      // C language  
    for (i = 0; i < N; i++)  
        a[i] = 2 * i;
```

```
!$omp parallel do           // Fortran  
    do i = 1, N  
        a(i) = 2 * i  
    end do
```

# Details

- By default, all variables in the work sharing region are shared except the loop iteration counter.
- Inside-loop variables which value depends on the loop index should be declared as private:

```
!$omp parallel do private(A)  
  do i = 1, N  
    A = 2 * i - 1  
    C(i) = sqrt(A)+log10(A)-log(A)  
  end do
```



# Compiling / running

- If OpenMP code is compiled without `-openmp` switch, all OpenMP pragmas are ignored, and it is compiled as a serial code.
- If you add `-openmp` switch, a multi-threaded binary is generated. In interactive use, the environment variable `OMP_NUM_THREADS` is used to specify the number of threads. When submitting to the scheduler, the threaded queue should be used:

```
sqsub -q threaded -n 24 -o out -r 3d ./code
```

Running your code in parallel

Semi-automatic parallelization: OpenACC



# Introduction

- OpenACC is an equivalent of OpenMP, for GPU computing.
- SHARCNET has two GPU clusters:
  - angel (44 older GPUs; not good for double precision);
  - monk (108 newer GPUs; good for double precision)
- Only one compiler – PGI – has openACC support. To use it on angel/monk:

```
module unload intel  
module load pgi
```

# Simplest case

- As in OpenMP, the obvious targets for OpenACC are data-independent loops.  
Examples:

```
#pragma acc kernels loop      // C language
  for (i = 0; i < N; i++)
    a[i] = 2 * i;
```

```
!$acc kernels loop          // Fortran
  do i = 1, N
    a(i) = 2 * i
  end do
```



# Caveat

- The important difference from OpenMP: as loops which are being parallelized under OpenACC will have to copy all the input/output data between CPU and GPU via a relatively slow PCI-E link, the loop content has to be CPU-intensive (flop/byte ratio has to be high).
  - Bad flop/byte ratio:

```
for (i=0; i<N; i++)  
    A[i] = B[i] + C[i];
```
  - Better flop/byte ratio:

```
for (i=0; i<N; i++) {  
    A = 2*i - 1.0;  
    C[i] = sqrt(A) + log10(A) - log(A); }
```

# Compiling / running

- To compile:

```
pgcc -Minfo=accel -fast -v -acc code.c  
pgf90 -Minfo=accel -fast -v -acc code.f
```

- To run interactively (on monk dev node, mon54):

```
./code
```

- To submit to the scheduler (angel, monk):

```
sqsub -q gpu -o out -r 1d ./code
```



# Summary

# Final remarks

- With the exception of plain serial farming, all the considered parallelizing approaches result in a multi-threaded code, and hence can only be run on a single node (shared memory environment).
- The first two methods (serial farming with and without pagecache feature) require no source code, and can be utilized with a binary code (e.g. commercial).
- Only the last two methods (OpenMP and OpenACC) require some code modifications.



